

<b>March 6th</b>			
	<b>Room1 (1204)</b>	<b>Room2 (1205)</b>	<b>Room3 (1206)</b>
9:30-11:30	<b>SS2: New Actuation Technology for Mechatronic Systems</b>	<b>TT1: Automotive Mobile System 1</b>	<b>TT2: Measurement and Diagnosis</b>
11:30-13:00	<b>Break</b>		
	<b>Niwa Hall</b>		
13:00-13:10	<b>Opening</b>		
13:10-14:05	<b>Plenary Session 1: Dr.-Ing. habil. Valentin Ivanov, "Challenges of Integrated Vehicle Chassis Control: Some Findings of The European Project EVE"</b>		
14:05-15:00	<b>Plenary Session 2: Prof.Dr. Georg Schitter "System Integration and Control of Mechatronic Imaging Systems"</b>		
15:00-15:30	<b>Break</b>		
	<b>Room1 (1204)</b>	<b>Room2 (1205)</b>	<b>Room3 (1206)</b>
15:30-17:30	<b>IS2: What is the Key to Future Haptics?</b>	<b>TT3: Automotive Mobile System 2</b>	<b>TT4: Actuation and Control</b>

<b>March 7th</b>			
	<b>Room1 (1204)</b>	<b>Room2 (1205)</b>	<b>Room3 (1206)</b>
9:30-11:30	<b>SS1: Estimation and Information in Motion Control</b>	<b>TT5: Biomechanical Control</b>	<b>TT6: Precision Control</b>
11:30-13:00	<b>Break</b>		
13:00-14:40	<b>IS1: High Precision Motion Control in Mechatronic Systems</b>	<b>TT7: Rehabilitation and Welfare Applications</b>	<b>TT8: Advanced Control Theory</b>
14:40-15:10	<b>Break</b>		
	<b>Room1 (1204)</b>		
15:10-16:05	<b>Tutorial 1: Prof. Michael Ruderman "Feedback relay systems: established approaches and new perspectives for application"</b>		
16:05-17:00	<b>Tutorial 2: Prof. Hyungbo Shim "Underlying theory of disturbance observers with large bandwidth of Q-filter"</b>		
17:30-19:30	<b>Banquet Building No.3 2nd Floor, Restaurant</b>		

<b>March 8th</b>			
	<b>Room1 (1204)</b>	<b>Room2 (1205)</b>	<b>Room3 (1206) / Poster Space</b>
9:30-11:30		<b>TT9: Robotics and Mechatronics 1</b>	<b>V1: Video and Interactive Session 1</b>
11:30-13:00	<b>Break / Demonstration</b>		
13:00-15:00	<b>IS3: Intelligent Sensing Applications for Human Support Systems</b>	<b>TT10: Control and Power Electronics</b>	<b>V2: Video and Interactive Session 2</b>
15:00-15:30	<b>Break</b>		
15:30-17:30		<b>TT11: Robotics and Mechatronics 2</b>	<b>V3: Video and Interactive Session 3</b>