

| March 6th | | | | | | | | | |
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| Session Room 1 (1204) | | | Session Room 2 (1205) | | | Session Room 3 (1206) | | | |
| SS2: New Actuation Technology for Mechatronic Systems | | | TT1: Automotive Mobile System 1 | | | TT2: Measurement and Diagnosis | | | |
| Prof. Yasutaka Fujimoto | | | Prof. Valentin Ivanov | | | Prof. Naoki Oda | | | |
| Prof. Tomoyuki Shimono | | | Dr. Takashi Yamaguchi | | | Prof. Satoshi Suzuki | | | |
| Title | | First Autor | Title | | First Autor | Title | | First Autor | |
| 9:30-11:30 | SS2-1 | Analysis of The Cross-Coupled Two-Degree-of-Freedom Motor with Coil Back Yoke | Yoshiyuki Hatta (Yokohama National University) | TT1-1 | Basic Study on Range Extension Autonomous Driving Considering Uncertainty of Signal Information | Naoyuki Ogawa (The University of Tokyo) | TT2-1 | Development of an Angle Measurement System Using Monocular Camera and Moiré Patterns | Junya Tsunoda (Saitama University) |
| | SS2-2 | Proposal of Load-side Encoder Based Slip Ratio Estimation Method for 4-wheeled In-wheel-motor with Reduction Gear | Tomoki Emmei (The University of Tokyo) | TT1-2 | Experimental Verification of Localization by Optimization Considering Occupancy | Toshifumi Matsuno (Yokohama National University) | TT2-2 | An ANN for Estimation of Power Consumption of EV/HEV for Real Time Battery Diagnosis | Minella Bezha (Doshisha University) |
| | SS2-3 | Design Analysis for A Novel Wireless Resonant Actuator | Besong John Ebot (Yokohama National University) | TT1-3 | Dynamic Voltage Control for Maximum Efficiency Operation of WPT with Secondary-side Supercapacitor | Kensuke Hanajiri (The University of Tokyo) | TT2-3 | Drowsiness Estimation using RR Interval Variation for Vehicle | Takaya Sano (Chuo University) |
| | SS2-4 | Simultaneous design of linear motion and power-saving magLev control of helical motor | Masato Koyama (Mie University) | TT1-4 | Experimental Study on Optimal Formation Control System for Autonomous Swarm Robot | Toshiki Midorikawa (National Institute of Technology, Gunma College) | TT2-4 | Heat Inflow Control under the Heat Interference Using Environment Quarrier | Yuji Kimura (Keio University) |
| | SS2-5 | Radial-Gap Helical RotLin Machine Attainment as an Alternative of New Actuation Technologies | Christophe Cyusa (Yokohama National University) | TT1-5 | Speed Control of Tilling Claw Considering Periodic Reaction Torque of Electric Tiller | Junichi Fukui (Nagaoka University of Technology) | TT2-5 | Object and person recognition method using deep learning for service robot | Hiroshi Sugano (Shibaura Institute of Technology) |
| | SS2-6 | Comparison of a Voice Coil and a Hybrid Reluctance Actuator via FEM | Francesco Cigarini (Vienna University of Technology) | TT1-6 | Detection of Road Direction Using 2D LRF in Unknown Environment | Ryo Toshimitsu (Yokohama National University) | | | |
| 11:30-13:00 Break | | | | | | | | | |
| 13:00-13:10 Niwa Hall Opening | | | | | | | | | |
| 13:10-14:05 Plenary Session 1: Dr.-Ing. habil. Valentin Ivanov, "Challenges of Integrated Vehicle Chassis Control: Some Findings of The European Project EVE" | | | | | | | | | |
| 14:05-15:00 Plenary Session 2: Prof.Dr. Georg Schitter, "System Integration and Control of Mechatronic Imaging Systems" | | | | | | | | | |
| 15:00-15:30 Break | | | | | | | | | |
| Session Room 1 (1204) | | | Session Room 2 (1205) | | | Session Room 3 (1206) | | | |
| IS2: What is the Key to Future Haptics? | | | TT3: Automotive Mobile System 2 | | | TT4: Actuation and Control | | | |
| Prof. Toshiaki Tsuji | | | Pro. Toshimasa Miyazaki | | | Prof. Kiyoshi Ohishi | | | |
| Prof. Yosuke Asano | | | Prof. Chowarit Mitsantisuk | | | Prof. Michael Ruderman | | | |
| Title | | First Autor | Title | | First Autor | Title | | First Autor | |
| 15:30-17:30 | IS2-1 | Functional Haptic Actuators for Human Support Applications | Tomoyuki Shimono (Yokohama National University) | TT3-1 | Minimum-time Maneuver and Friction Coefficient Estimation Using Slip Ratio Control for Autonomously-Driven Electric Vehicle | Hiroyuki Fuse (The University of Tokyo) | TT4-1 | Analysis of Low-Cogging PM Motor for Highly Backdrivable Actuators | Hiroyuki Noma (Yokohama National University) |
| | IS2-2 | Fine Torsion Torque Control for Vibration Suppression of Load-side Acceleration and Its Internal Stability | Yuki Yokokura (Nagaoka University of Technology) | TT3-2 | Mobile Control with Two-wheeled Inverted Pendulum Robot for Human Following | Kanji Ubukata (Shibaura Institute of Technology) | TT4-2 | Development of motor using heat-pipe mechanism | Akihiro Katsuno (Keio University) |
| | IS2-3 | How Can We Apply Our Haptic Technologies to Scientific Studies? | Masayuki Hara (Saitama University) | TT3-3 | Mechanical-Backlash-based Minimum Jerk Final-state Control for Shockless Clutch Engagement | Akira Yamaguchi (Nagaoka University of Technology) | TT4-3 | Design and analysis of multi-layered coreless permanent magnet synchronous motor | Koki Sakuma (Yokohama National University) |
| | IS2-4 | FingerVision for Tactile Behaviors, Manipulation, and Haptic Feedback Teleoperation | Akihiko Yamaguchi (Tohoku University) | TT3-4 | A Simplification of Motion Generation Method in the Singular Configuration of a Wheel-Legged Mobile Robot | Kenta Nagano (Yokohama National University) | TT4-4 | Analysis of Indirect Force Control System which Includes Close-loop Velocity Control System Using Ultrasonic Motor | Daiki Yonemoto (Mie University) |
| | | | | TT3-5 | An Attitude Control considering Sideslip Phenomenon for Four-Wheel Steering Vehicle | Hironu Soubou (Shibaura Institute of Technology) | TT4-5 | The Robustness Verification of Motor Ripple Reduction System | Yuma Itokawa (Mie University) |
| | | | | TT3-6 | Fundamental Study of Four Wheel Steering System without Rear Steer Actuator for Four Wheel Driving Electric Vehicles | Kota Miyahara (The University of Tokyo) | | | |